

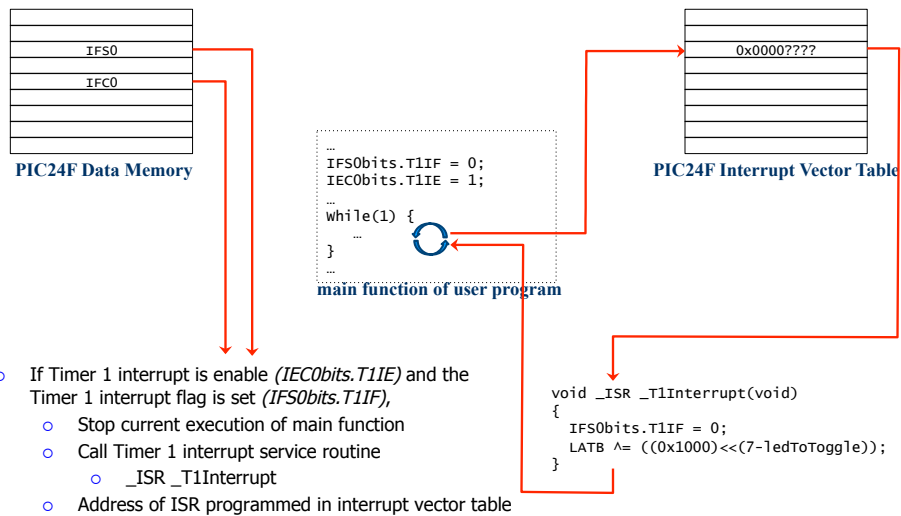
# ECE 372 – Microcontroller Design

## Interrupts



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### ○ PIC24F

- 118 interrupts vectors
- Unique vector for each possible interrupt
- Compiler support for defining ISR for all possible interrupt using interrupt name

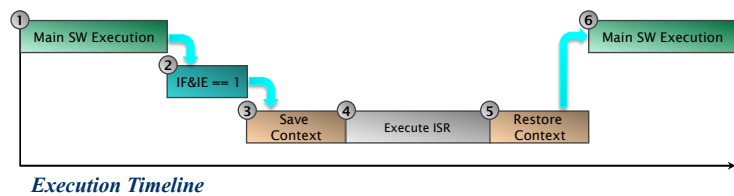
FIGURE 7-1: PIC24F INTERRUPT VECTOR TABLE

Reset - GOTO Instruction	000000h
Reset - GOTO Address	000002h
Reserved	000004h
Oscillator Fail Trap Vector	
Address Error Trap Vector	
Stack Error Trap Vector	
Math Error Trap Vector	
Reserved	
Reserved	
Interrupt Vector 0	000014h
Interrupt Vector 1	
...	
...	
Interrupt Vector 52	00007Ch
Interrupt Vector 53	00007Eh
Interrupt Vector 54	000080h
...	
...	
Interrupt Vector 116	0000FCh
Interrupt Vector 117	0000FEh
Reserved	000100h
Reserved	000102h
Reserved	
Oscillator Fail Trap Vector	
Address Error Trap Vector	
Stack Error Trap Vector	
Math Error Trap Vector	
Reserved	
Reserved	
Interrupt Vector 0	000114h
Interrupt Vector 1	
...	
...	
Interrupt Vector 52	00017Ch
Interrupt Vector 53	00017Eh
Interrupt Vector 54	000180h
...	
...	
Interrupt Vector 116	0001FCh
Interrupt Vector 117	0001FEh
Start of Code	000200h

Note 1: See Table 7-2 for the interrupt vector list.

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## Interrupts



### ○ Interrupt Execution Timeline

- Interrupts are checked every execution cycle
- Interrupt service will save restore the execution context of the main execution loop at the begin and end of ISR execution
  - Saves all working registers and program counter
  - Automatically handled by compiler

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### Defining Interrupts

#### ○ Microchip Compiler for PIC24 Support

- Interrupts can be defined primarily in two ways
- Option 1 (*direct/verbose method*)

```
void __attribute__((interrupt)) _CNInterrupt(void)
{
    // interrupt code goes here
}
```

- Option 2 (*using #defines in p24fj64ga002.h*)

```
void _ISR_T1Interrupt(void)
{
    // interrupt code goes here
}
```

- Compiler has defined names for

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### Defining Interrupts

#### ○ Microchip Compiler for PIC24 Support

- Compiler has defined names for all interrupts
  - Example: `_T1Interrupt` : Timer 1
  - Example: `_CNInterrupt` : Change Notification Interrupt

0	<code>_INT0Interrupt</code>	<code>_AIINT0Interrupt</code>	INT0 External interrupt 0
1	<code>_IC1Interrupt</code>	<code>_AIIIC1Interrupt</code>	IC1 Input capture 1
2	<code>_OC1Interrupt</code>	<code>_AIIOC1Interrupt</code>	OC1 Output compare 1
3	<code>_T1Interrupt</code>	<code>_AIT1Interrupt</code>	TMR1 Timer 1 expired
4	<code>_IC2Interrupt</code>	<code>_AIIIC2Interrupt</code>	IC2 Input capture 2
5	<code>_OC2Interrupt</code>	<code>_AIIOC2Interrupt</code>	OC2 Output compare 2
6	<code>_T2Interrupt</code>	<code>_AIT2Interrupt</code>	TMR2 Timer 2 expired
7	<code>_T3Interrupt</code>	<code>_AIT3Interrupt</code>	TMR3 Timer 3 expired
8	<code>_SPI1Interrupt</code>	<code>_AISPI1Interrupt</code>	SPI1 Serial peripheral interface 1
9	<code>_U1RXInterrupt</code>	<code>_AIU1RXInterrupt</code>	UART1RX Uart 1 Receiver
10	<code>_U1TXInterrupt</code>	<code>_AIU1TXInterrupt</code>	UART1TX Uart 1 Transmitter
11	<code>_ADCInterrupt</code>	<code>_AIIADCInterrupt</code>	ADC convert completed
12	<code>_NVMInterrupt</code>	<code>_AINVMInterrupt</code>	NMM NVM write completed
13	<code>_SI2CInterrupt</code>	<code>_AISI2CInterrupt</code>	Slave I <sup>2</sup> C™ interrupt
14	<code>_MI2CInterrupt</code>	<code>_AIMI2CInterrupt</code>	Master I <sup>2</sup> C interrupt
15	<code>_CNInterrupt</code>	<code>_AIIICNInterrupt</code>	CN Input change interrupt
16	<code>_INT4Interrupt</code>	<code>_AIINT4Interrupt</code>	INT4 External interrupt 0

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### Defining Interrupts

- Guidelines for ISRs
  - Declare ISRs with no parameters
  - Do **NOT** call functions
  - Do **NOT** call main code or functions
  - Do **NOT** call ISRs from the main code
  - ISR should be as short as possible and return as quickly as possible
  - ISR **MUST** reset interrupt flag
    - *What happens if we don't?*
  - Variables shared between ISR and main code **MUST** be declared as **volatile**
    - **volatile** keyword in C indicates to compiler not to store value within register, but to always write value back to memory
    - Ensures consistent value is maintained between ISR and main code
      - i.e., value is not stored in register that will be saved and restored during call to the ISR